

automated electric press brake



electric press brake



general catalogue

euromac electric press brake



manufactured with a variety of production configurations, of your own choice.

With our cell it will be easy and fast to launch any production

Integrated structure between machine

The system originates as unique element, with integrated robot as part of the structure of FX bend itself. An automated compact

developing every single element of the structure, from the machine and the robot integration, to the software that runs the production. A complete, reliable and friendly-use system.



The first cell configurable according to your production needs.

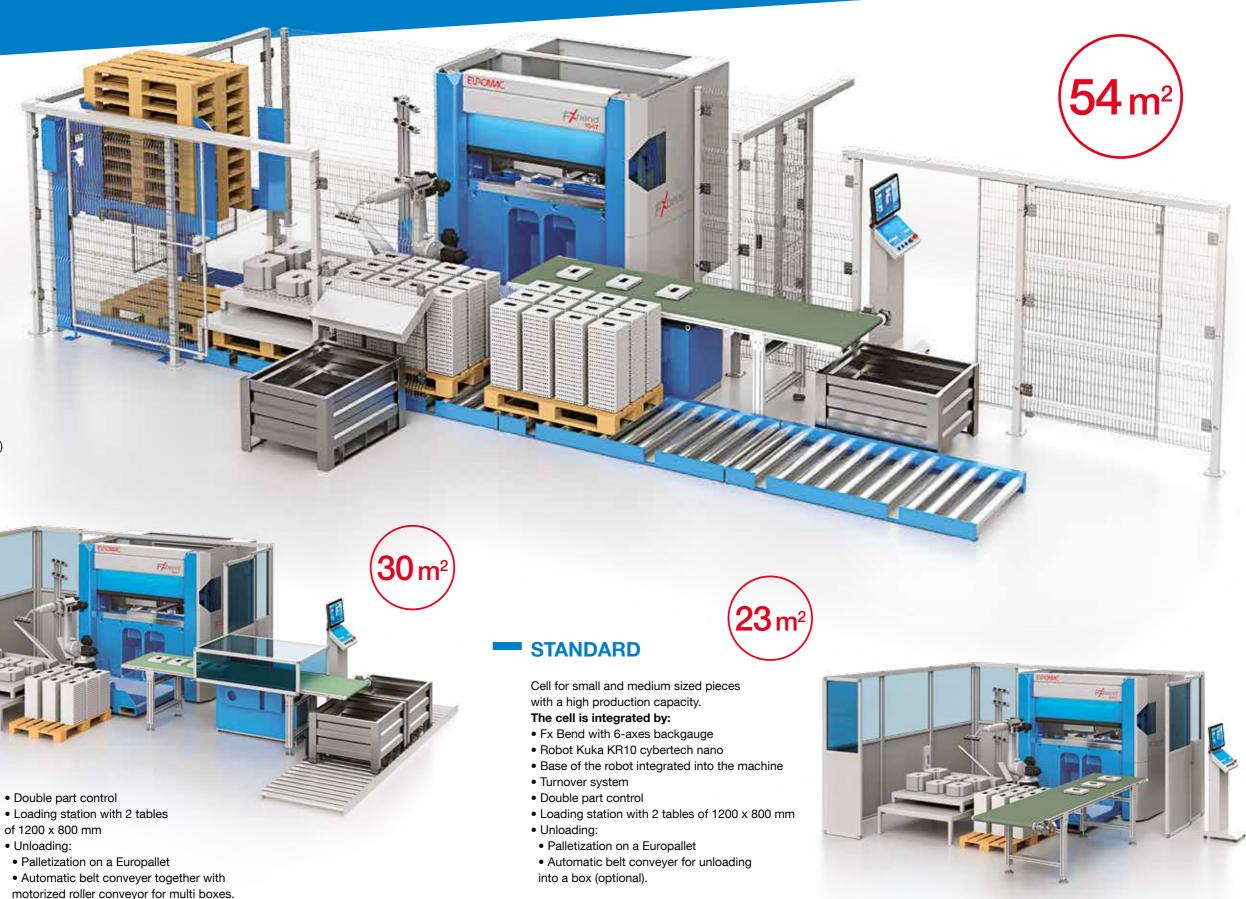
We configure the machine to your individual specification.

MAX

Cell for small and medium sized pieces with a high production capacity. The cell is integrated by:

- Fx Bend with 6-axis backgauge
- Robot Kuka KR10 cybertech nano
- Base of the robot integrated into the machine
- Turnover system
- Double part control
- Loading station with 2 tables of 1200 x 800 mm
- Unloading:
- · Palletization on a motorized roller conveyor for Europallet
- Vertical storage up to 10 Europallets (optional)
- Automatic belt with unloading into a box

(optional).





PLUS

Cell for small and medium sized pieces with a high production capacity. The cell is integrated by:

- Fx Bend with 6-axes backgauge.
- Robot Kuka KR10 cybertech nano.
- Base of the robot integrated into the machine
- Turnover system

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When productivity needs important performances.

The ideal solution for workpieces up to 1500 x 800mm. Large-capacity robot, with 2 different unloading configurations that can be modulated based on the customer productivity.

MAX

Cell for small and medium sized pieces with a high production capacity. The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60
- Base of the robot integrated into the machine
- Turnover system
- Double part control
- Loading station with 2 tables of 1500 x 800 mm
- Unloading:
- Vertical storage for 10 Europallet (optional)
- · Palletization on a motorized roller conveyor for Europallet
- Boxes for small pieces
- Automatic belt conveyer for unloading into a box (optional).





STANDARD

Cell for small and medium sized pieces with a high production capacity.

The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60
- · Base of the robot integrated into the machine
- Turnover system



- Double part control
- Loading station with 2 tables of 1500 x 800 mm
- Unloading:
- Palletization on 2 Europallet
- Automatic belt conveyer for unloading into a box (optional).



Think big. Solution for workpieces up to 2500x1000 mm with 7-axes KR 60 robot on rail.

Large-scale robot, available in 2 unloading configurations suitable to your productive needs.

MAX

Cell for medium and large sized pieces with a high production capacity. The cell is integrated by:

- Fx Bend with 6-axes backgauge
- Robot Kuka KR60 on rail
- Turnover system
- Double part control
- Loading station for pieces up to 2500 x 1000 mm
- Unloading:
- Vertical storage for 10 Europallet (optional)
- Box for small pieces

50 m

· Palletization on motorized roller conveyor for Europallet



Cell for medium and large sized pieces with a high production capacity. The cell is integrated by: • Fx Bend with 6-axes backgauge

Robot Kuka KR60 on rail



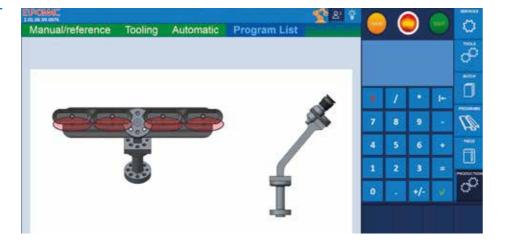
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SOFTWARE

ON LINE Standard software with parametrized programs.



FX CELL Supervisor

The added value is the extreme ease and speed in making any kind of modification to your work.

- With Fx Cell supervisor it is possible to: • modify all the parameters of the bending cells
- choose the right gripper and activate or deactivate the suction cups
- · select or modify the loading part position • select or modify the unloading
- position
- activate or deactivate the double metal sheet control

All this, working directly from the interface of our Fx Soft and without having to change anything from the program.

Everything at your fingertips in a simple and fast way.

SOFTWARE OFF LINE



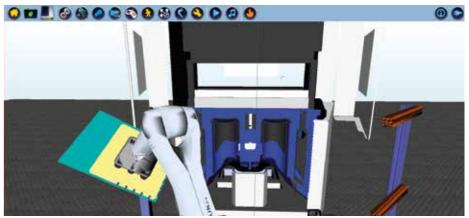


Fast and simplified programming even for more complex requirements.

The offline programming software works in perfect cohesion with the FX bend cell, becoming a complementary optional item allowing to quickly anticipate the movements, the processing efficiency and eventually acting to optimize it. Thanks to a 3D graphic display and the management of the palletization data, it's possible to have a complete operation vision and reduce production times.



- Reduce production stops due to
- programming time to a minimum. • Predict the efficiency of the workcell for any particular product and take
- action to improve it if necessary. • Simplify robot programming task.
- Easily visualize and setup palletizing data.





Possibility to put the robot in parking mode to work in manual mode inside the cell.





LOADING & UNLOADING



Maximum versatility of loading - unloading for any production requirement.

When designing a complete system, Euromac also paid great attention to the in-and outbound parts flow, to ensure a fast and reliable production. By anticipating multiple production needs, the FX bend cell offers a wide range of solutions for the loadingunloading operation.

Loading

Loading area with 2 pre-alignment tables. The pre-alignment table has a perforated die for the perfect positioning of the pieces.

With different loading zones according to the model 1000 x600 1500 x 800 2500 x1000 mm.

Optionally, we offer the possibility to have additional loading tables, to stack pieces next to a punching or a laser machine, and the easily moved to the cell with a forklift.

Unloading

Our automated work stations offer many unloading solutions, from palletization of parts on fixed europallets to 10-euro-pallet automatic towers, to motorized roller conveyors for fast unloading operations. It is also possible to position pieces directly in cases or on a conveyor belt to unload on a fixed case, or positioned on motorized rollers

COMBINATION OF UNLOADING Optional.

Belt conveyer unloading

Belt conveyer

unloading with

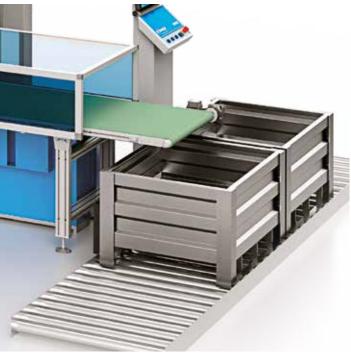
motorized boxes



Motorized Europallet unloading







GRIPPERS

Three standard gripper. Additional gripper to make special customer parts on request.





Gripper* with vacuum for big format parts, external dimension 430x280 with the possibility to insert up to 8 suction cups.

Max nominal part weight: 1.5 Kg (centered position).

FX bend cell is an automated bending cell combining production speed with high processing quality. The system guarantees a high standard of bending precision on any type of part, large or small.

APPLICATIONS



Gripper* with vacuum for medium format parts, external dimension 230x230 with the possibility to insert up to 10 suction cups.

Max nominal part weight: 5 Kg (centered position).



Gripper* with vacuum for small parts, with the possibility to insert from 3 up to 20 suction cups divided to maximum 8 independent zones.

Maximum nominal piece weight: 3 Kg. (in centered position).

*For a real feasibility is necessary to make a supplementary part inertia study where the part geometry is provided by the customer.

















F bend cell

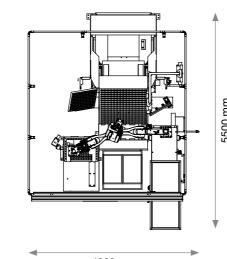
Machine range and productions





STANDARD

technical data	cell 1023	cell 1547
Max. bending force (kN)	230	470
Bending length (mm)	1020	1530
Daylight opening		
Wila clamping (die holder - to punch holder) (mm)	315	360
Promecam clamping (die holder - to ram) (mm)	395	440
Y axes stroke (mm)	196	240
Y axes speed (mm/sec)	200	200
Max. bending speed automatic mode (mm/sec)	36	36
Max. bending speed manual mode (mm/sec)	10	10
Robot		
Max. reach (mm)	1420	1420
Max. payload with gripper (kg)	10	10
Number of axes	6	6
Pose repeability (mm)	+-0.03	+-0.03
FX Cell		
Loading		
Minimum parts dimension (mm)	50 x 100	50 x 100
Maximum stack height (mm)	300	300
Maximum thicknes (mm)	5	5
Minimum thicknes (mm)	0,7	0,7
Maximum part weight (kg)	5	5
Unloading		
Belt conveyor buffer length (mm)	600 unloading +600	0 600 unloading +600
Area for gravity unloading (mm)	1200 x 800	1200 x 800
Connected load (kWa)	5	6
Approx. weight (kg)	3000	5000

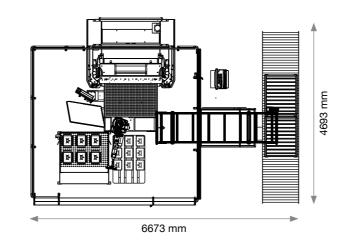


4200 mm



PLUS

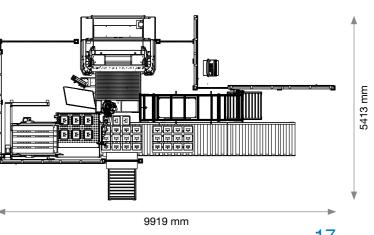
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Robot		
Max. reach (mm)	1420	1420
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Number of axes	6	6
Pose repeability (mm)	+-0.03	+-0.03
FX Cell		
Loading		
Minimum parts dimension (mm)	50 x 100	50 x 100
Maximum stack height (mm)	300	300
Maximum thicknes (mm)	5	5
Minimum thicknes (mm)	0,7	0,7
Maximum part weight (kg)	5	5
Unloading		
Belt conveyor buffer length (mm)	600 unloading +600	600 unloading +600
Area for gravity unloading (mm)	1200 x 800	1200 x 800
Connected load (kWa)	5	6
Approx. weight (kg)	3000	5500





MAX

echnical data	cell 1023	cell 1547
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axes stroke (mm)	196	240
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lax. bending speed automatic mode (mm/sec)	36	36
lax. bending speed manual mode (mm/sec)	10	10
obot		
lax. reach (mm)	1420	1420
lax. payload with gripper (kg)	10	10
umber of axes	6	6
ose repeability (mm)	+-0.03	+-0.03
X Cell		
pading		
linimum parts dimension (mm)	50 x 100	50 x 100
laximum stack height (mm)	300	300
laximum thicknes (mm)	5	5
linimum thicknes (mm)	0,7	0,7
laximum part weight (kg)	5	5
nloading		
elt conveyor buffer length (mm)	600 unloading +600	600 unloading + 600
rea for gravity unloading (mm)	1200 x 800	1200 x 800
onnected load (kWa)	5	6
pprox. weight (kg)	3000	6000

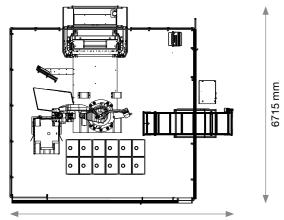


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STANDARD

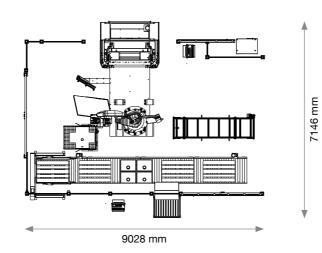
technical data	cell 1547
Max. bending force (kN)	470
Bending length (mm)	1530
Daylight opening	
Wila clamping (die holder - to punch holder) (mm)	360
Promecam clamping (die holder - to ram) (mm)	440
Y axes stroke (mm)	240
Y axes speed (mm/sec)	200
Max. bending speed automatic mode (mm/sec)	36
Max. bending speed manual mode (mm/sec)	10
Robot	
Max. reach (mm)	2233
Max. payload with gripper (kg)	60
Number of axes	6
Pose repeability (mm)	+-0.06
FX Cell	
Loading	
Maximum parts dimension 1 stack (mm)	1500 x 800
Minimum parts dimension (mm)	50 x 100
Maximum stack height (mm)	300
Maximum thicknes (mm)	5
Minimum thicknes (mm)	0,7
Maximum part weight (kg)	30
Unloading	
Belt conveyor Max. parts dimension (mm)	1000 x 600 x h 300
Belt conveyor buffer length (mm)	600 unloading + 600
Area for gravity unloading (mm)	1200 x 800
Connected load (kWa)	6
Approx. weight (kg)	6200



7583 mm

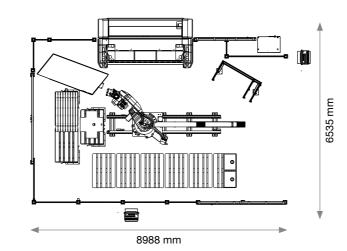


technical data	cell 1547
Max. bending force (kN)	470
Sending length (mm)	1530
Daylight opening	
Vila clamping (die holder - to punch holder) (mm)	360
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axes stroke (mm)	240
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lax. bending speed automatic mode (mm/sec)	36
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obot	
ax. reach (mm)	2233
ax. payload with gripper (kg)	60
umber of axes	6
se repeability (mm)	+-0.06
(Cell	
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aximum parts dimension 1 stack (mm)	1500 x 800
nimum parts dimension (mm)	50 x 100
aximum stack height (mm)	300
aximum thicknes (mm)	5
inimum thicknes (mm)	0,7
aximum part weight (kg)	30
Iloading	
It conveyor Max. parts dimension (mm)	1000 x 600 x h 300
It conveyor buffer length (mm)	600 unloading + 600
	1200 x 800
ea for gravity unloading (mm)	
ea for gravity unloading (mm) onnected load (kWa)	6



STANDARD

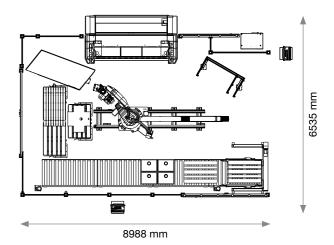
technical data	cell 2560
Max. bending force (kN)	500 / 600
Bending length (mm)	2550
Daylight opening	
Wila clamping (die holder - to punch holder) (mm)	360
Promecam clamping (die holder - to ram) (mm)	440
Y axes stroke (mm)	240
Y axes speed (mm/sec)	200
Max. bending speed automatic mode (mm/sec)	36
Max. bending speed manual mode (mm/sec)	10
Robot	
Max. reach (mm)	2233
Max. payload with gripper (kg)	60
Number of axes	7
Pose repeability (mm)	+-0.06
FX Cell	
Loading	
Maximum parts dimension 1 stack (mm)	2500 x 1000
Minimum parts dimension (mm)	50 x 100
Maximum stack height (mm)	300
Maximum thicknes (mm)	5
Minimum thicknes (mm)	0,7
Maximum part weight (kg)	30
Unloading	
Area for gravity unloading (mm)	1200 x 800
Connected load (kWa)	6
Approx. weight (kg)	8500





MAX

technical data	cell 2560
Max. bending force (kN)	500 / 600
Bending length (mm)	2550
Daylight opening	
Wila clamping (die holder - to punch holder) (mm)	360
Promecam clamping (die holder - to ram) (mm)	440
Y axes stroke (mm)	240
Y axes speed (mm/sec)	200
Max. bending speed automatic mode (mm/sec)	36
Max. bending speed manual mode (mm/sec)	10
Robot	
Max. reach (mm)	2233
Max. payload with gripper (kg)	60
Number of axes	7
Pose repeability (mm)	+-0.06
FX Cell	
Loading	
Maximum parts dimension 1 stack (mm)	2500 x 1000
Minimum parts dimension (mm)	50 x 100
Maximum stack height (mm)	300
Maximum thicknes (mm)	5
Minimum thicknes (mm)	0,7
Maximum part weight (kg)	30
Unloading	
Area for gravity unloading (mm)	1200 x 800
Connected load (kWa)	6
Approx. weight (kg)	9500



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sheet metal working center



automated electric press brake



electric press brake



horizontal bending machines



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notching machines



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